



SmartPark Research Project Update

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Federal Motor Carrier Safety Administration
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Office of Research and Information Technology

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Outline

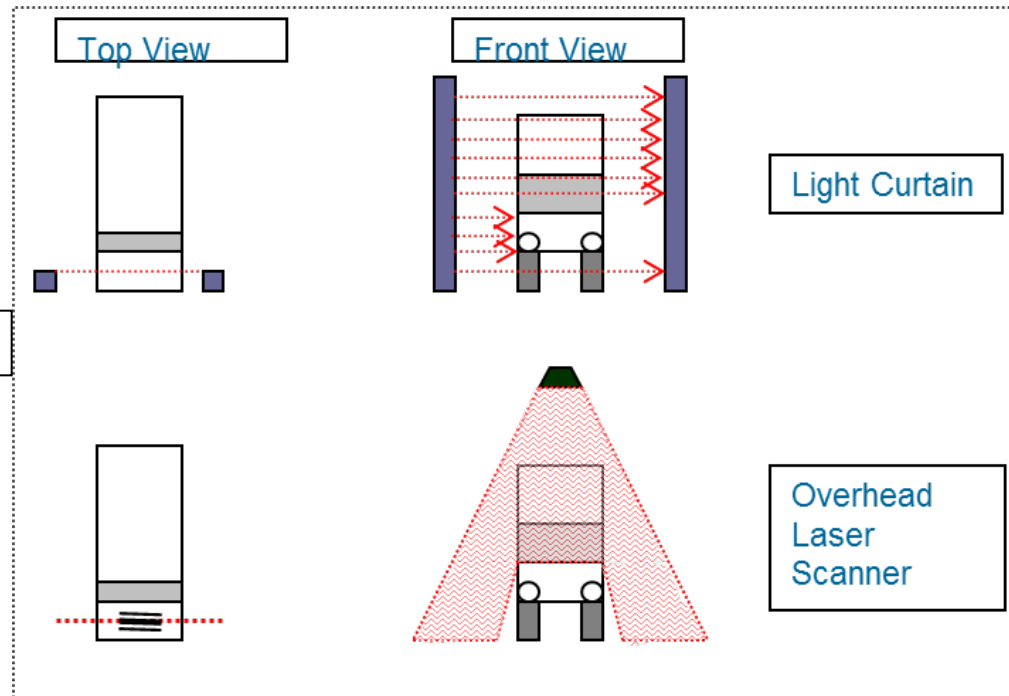
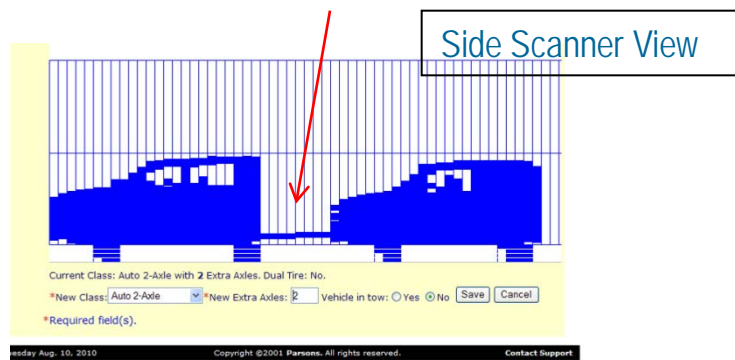
- Purpose
- Phase I
- Test Site
- Performance Requirements
- Test Results
- Phase II

Purpose

- To demonstrate a fully automated solution for providing truck parking availability information to truckers on the road
 - Phase I – to evaluate technologies that can automatically measure truck parking space availability in a rest area
 - Phase II – to disseminate truck parking space availability information in real time to truck drivers and to evaluate overall benefits

Phase I

- In 2011, FMCSA initiated Phase I to evaluate new vehicle detection sensors – Doppler radar combined with either light curtain or laser scan
- In prior testing, magnetic and camera-based sensors could not accurately distinguish vehicle types or trailer drop offs and pick ups.
- New Phase I sensors produce a top or side profile from which software can detect a hitch



Test Site Location – Athens, TN



Test Site at Mile Marker 45 on I-75 northbound

Test Site Characteristics

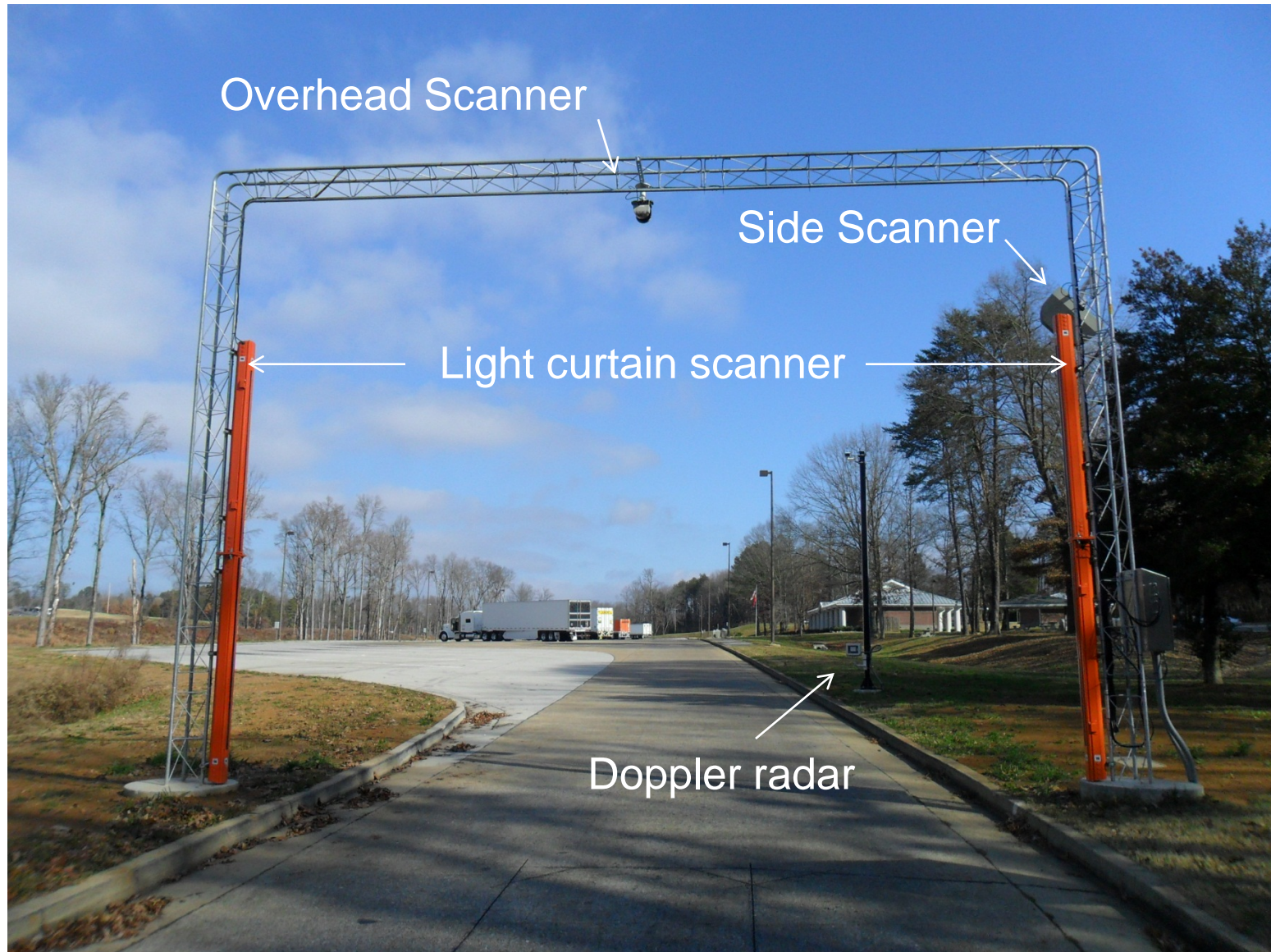
Egress
I-75 northbound
Truck parking area
Car parking area
Ingress



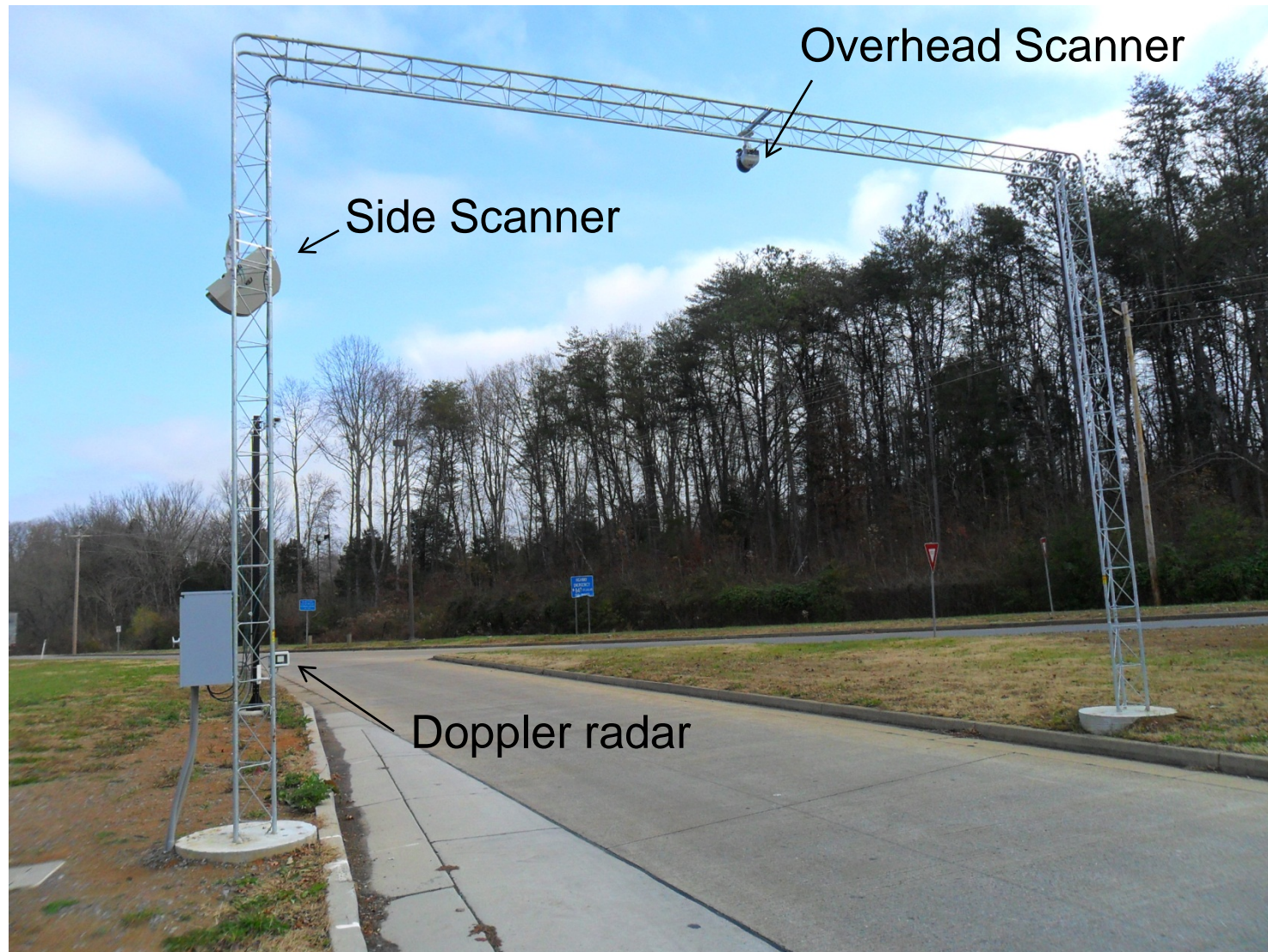
■ Characteristics

- Site is paved
- Truck parking clearly separated from car parking
- One ingress and one egress, both controlled
- 44 delineated, marked spaces for trucks
- Designed so trucks can easily pull-in & pull-out

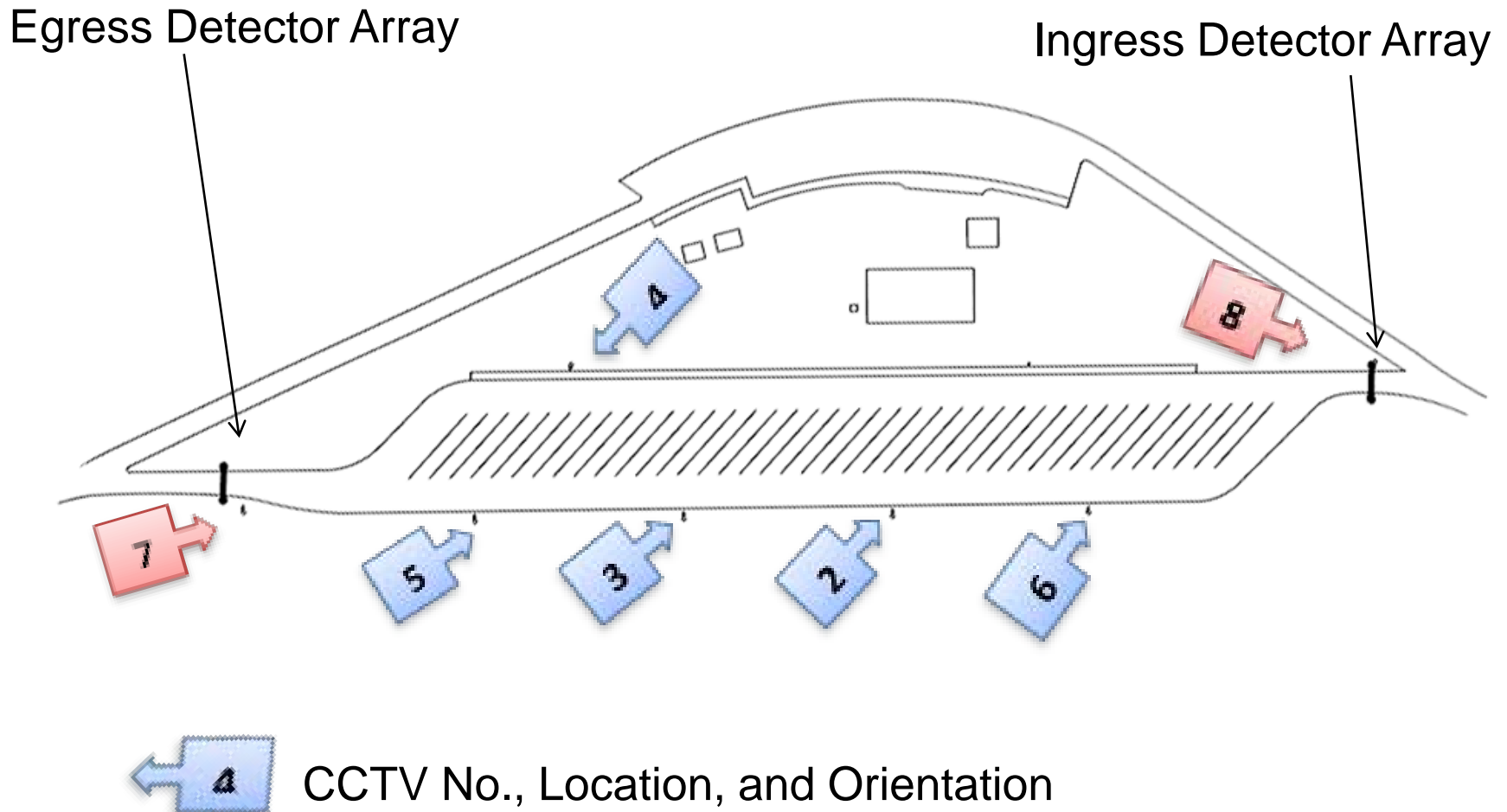
Test Site Ingress – Technology Array



Test Site Egress – Technology Array



Sensor Data Verification with CCTV



Performance Requirements

Requirement Identification	Description
PR1 – Accuracy	System shall maintain the parking area occupancy count at $\geq 95\%$ accuracy.
PR2 – Classification Consistency	Ingress and egress detectors must be consistent in classification with each other at $\geq 95\%$.
PR3 – Uptime for System	System shall provide parking availability information at a minimum of 99.5% of the time.

Phase I Test Results

Requirement		Gannett-Fleming	Independent Assessment
Descriptor	%	11/18-11/21 in 2012 N=459, overhead scans	12/10-12/13 in 2012 N=1340, side scans
PR1 – Accuracy	≥ 95	98.3%	99.9%
PR2 – Classification Consistency	≥ 95	97.4%	99.0%
PR3 – Uptime for System	≥ 99.5	100%	100%

Phase II

- Field test to evaluate benefits of measuring and providing dynamic parking information to truck drivers in real time
- Tasks (6/22/2013 – 11/21/2014)
 1. Disseminating truck parking availability information
 2. Linking two adjacent truck parking rest areas
 3. Adding reservation capability to system
 4. Recruiting participating fleets and other partners
 5. Conducting field test
 6. Documenting field test results and assessing benefits
 7. Developing a technology transition/business plan

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